Safety Manual for Fisher™ 1061 Actuator

Purpose

This safety manual provides information necessary to design, install, verify and maintain a Safety Instrumented Function (SIF) utilizing the Fisher 1061 pneumatic piston rotary actuator.

⚠ WARNING

This instruction manual supplement is not intended to be used as a stand-alone document. It must be used in conjunction with the following manuals:
Fisher 1061 Pneumatic Piston Rotary Actuator with Style G & F Mounting Adaptations Instruction Manual (D100324X012)
Fisher 1061 Pneumatic Piston Rotary Actuator with Style H & J Mounting Adaptations Instruction Manual (D100325X012)
Failure to use this instruction manual supplement in conjunction with the above referenced manuals could result in personal injury or property damage. If you have any questions regarding these instructions or need assistance in obtaining any of these documents, contact your Emerson sales office.

Introduction

This manual provides necessary requirements for meeting the IEC 61508 or IEC 61511 functional safety standards.

Figure 1. Fisher 1061 Actuator


W8380-2

1061 Actuator with FIELDVUE™ DVC6200 Digital Valve Controller Mounted on a Fisher V500 Valve


W4142

H Mounting Adaptation


W4257-1

J Mounting Adaptation and Fisher 3610JP Positioner

Terms and Abbreviations

Safety: Freedom from unacceptable risk of harm.

Functional Safety: The ability of a system to carry out the actions necessary to achieve or to maintain a defined safe state for the equipment / machinery / plant / apparatus under control of the system.

Basic Safety: The equipment must be designed and manufactured such that it protects against risk of injury to persons by electrical shock and other hazards and against resulting fire and explosion. The protection must be effective under all conditions of the nominal operation and under single fault condition.

Safety Assessment: The investigation to arrive at a judgment - based on the facts - of the safety achieved by safety-related systems.

Fail-Safe State: State where valve actuator is driven to or held in a predefined position by the control medium.

Fail Safe: Failure that causes the valve to go to the defined fail-safe state without a demand from the process.

Fail Dangerous: Failure that does not respond to a demand from the process (i.e. being unable to go to the defined fail-safe state).

Fail Dangerous Undetected: Failure that is dangerous and that is not being diagnosed by automatic stroke testing.

Fail Dangerous Detected: Failure that is dangerous but is detected by automatic stroke testing.

Fail Annunciation Undetected: Failure that does not cause a false trip or prevent the safety function but does cause loss of an automatic diagnostic and is not detected by another diagnostic.

Fail Annunciation Detected: Failure that does not cause a false trip or prevent the safety function but does cause loss of an automatic diagnostic or false diagnostic indication.

Fail No Effect: Failure of a component that is part of the safety function but that has no effect on the safety function.

Low demand mode: Mode, where the frequency of demands for operation made on a safety-related system is no greater than twice the proof test frequency.

Acronyms

FMEDA: Failure Modes, Effects and Diagnostic Analysis

HFT: Hardware Fault Tolerance

MOC: Management of Change. These are specific procedures often done when performing any work activities in compliance with government regulatory authorities.

PFD_{AVG}: Average Probability of Failure on Demand

SFF: Safe Failure Fraction, the fraction of the overall failure rate of a device that results in either a safe fault or a diagnosed unsafe fault.

SIF: Safety Instrumented Function, a set of equipment intended to reduce the risk due to a specific hazard (a safety loop).

SIL: Safety Integrity Level, discrete level (one out of a possible four) for specifying the safety integrity requirements of the safety functions to be allocated to the E/E/PE safety-related systems where Safety Integrity Level 4 has the highest level of safety integrity and Safety Integrity Level 1 has the lowest.

SIS: Safety Instrumented System – Implementation of one or more Safety Instrumented Functions. A SIS is composed of any combination of sensor(s), logic solver(s), and final element(s).

Related Literature

Hardware Documents:

Bulletin:

61.1:1061, Fisher 1061 Pneumatic Piston Rotary Actuator (D100095X012)

Instruction Manual:

Fisher 1061 Pneumatic Piston Rotary Actuator with Style F & G Mounting Adaptations Instruction Manual (D100324X012)
Fisher 1061 Pneumatic Piston Rotary Actuator with Style H & J Mounting Adaptations Instruction Manual (D100325X012)

Guidelines/References:

- Safety Integrity Level Selection – Systematic Methods Including Layer of Protection Analysis, ISBN 1-55617-777-1, ISA
- Control System Safety Evaluation and Reliability, 2nd Edition, ISBN 1-55617-638-8, ISA
- Safety Instrumented Systems Verification, Practical Probabilistic Calculations, ISBN 1-55617-909-9, ISA

Reference Standards

Functional Safety

- IEC 61508: 2010 Functional safety of electrical/electronic/ programmable electronic safety-related systems
- ANSI/ISA 84.00.01-2004 (IEC 61511 Mod.) Functional Safety – Safety Instrumented Systems for the Process Industry Sector

Product Description

The 1061 actuator is a double-acting pneumatic piston rotary actuator for use with rotary-shaft valves having splined valve shafts. The 1061 actuator can be used for either throttling or on-off applications.

The 1061 actuator is a pneumatic piston rotary actuator for use with rotary control valves and other equipment.

1061 H and J mountings are available in actuator sizes 30, 40, 60, and 68. The H mounting adaptation permits the actuator to be used with user-provided mounting brackets and couplings for rotary actuation of equipment other than Fisher valves. The J mounting adaptation permits the actuator to be used for rotary actuation of Fisher keyed-shaft butterfly valves and other keyed-shaft equipment that can mount on the actuator yoke.

The H mounting adaptation includes a flat-surface mounting plate that is drilled and tapped for attaching the user-provided bracket. Cap screws for attaching the bracket are provided. H mounting also includes an output shaft (with milled flats) to provide the rotary output either directly or through a user-provided coupling.

The J mounting adaptation uses the standard butterfly valve mounting bracket and provides an output shaft with an attached coupling for keyed equipment shafts.

The style G mounting bracket is for Fisher 9500 valves only. The style F mounting bracket is for all other rotary valves. 1061 F and G mountings are available in actuator sizes 30, 40, 60, 68, 80, 100, and 130.

For auxiliary manual operation of the equipment, a side-mounted handwheel actuator is available.

Designing a SIF Using a Fisher 1061 Actuator

Safety Function

The double-acting springless 1061 actuator constructions will maintain functionality so the actuator can be moved into the application dependent safe state by means of the control medium.

The 1061 actuator is intended to be part of final element subsystem as defined per IEC 61508 and the achieved SIL level of the designed function must be verified by the designer.

Environmental limits

The designer of an SIF must check that the product is rated for use within the expected environmental limits. Refer to the Fisher 1061 Pneumatic Piston Rotary Actuator Product Bulletin (D100095X012) for environmental limits.

Application limits

The 1061 actuator materials of construction are specified in the product bulletin. A range of materials are available for various applications. The serial card will indicate what the materials of construction are for a specific actuator. It is especially important that the designer check for material compatibility considering on-site chemical contaminants and air supply conditions. If the 1061 actuator is used outside of the application limits or with incompatible materials, the reliability data provided becomes invalid.

Diagnostic Response Time

A 1061 actuator does not perform any automatic diagnostic functions by itself and therefore it has no diagnostic response time of its own. However, automatic diagnostics of the final control subsystem may be performed such as Partial Valve Stroke Testing (PVST). This typically will exercise the actuator and valve over a small percentage of its normal travel without adversely affecting the flow through the valve. If any failures of this PVST are automatically detected and annunciated, the diagnostic response time will be the PVST interval time. The PVST must be performed 10 times more often than an expected demand in order for credit to be given for this test.

Design Verification

A detailed FMEDA report is available from Emerson. This report details all failure rates and failure modes as well as the expected lifetime.

The achieved SIL of an entire SIF design must be verified by the designer via a calculation of PFD_{AVG} considering architecture, proof test interval, proof test effectiveness, any automatic diagnostics, average repair time and the specific failure rates of all products included in the SIF. Each subsystem must be checked to assure compliance with minimum HFT requirements.

When using a 1061 actuator in a redundant configuration, a common cause factor of at least 5% should be included in the Safety Integrity calculations. This value is dependent on the level of common cause training and maintenance in use at the end user's facility.

The failure rate data listed the FMEDA report is only valid for the useful lifetime of a 1061 actuator. The failure rates will increase after this time period. Reliability calculations based on the data listed in the FMEDA report for mission times beyond the useful lifetime may yield results that are too optimistic, i.e. the calculated Safety Integrity Level will not be achieved.

SIL Capability

Systematic Integrity

Figure 2. exida SIL 3 Capable

The product has met manufacturer design process requirements of SIL 3. These are intended to achieve sufficient integrity against systematic errors of design by the manufacturer. A SIF designed with this product must not be used at a SIL level higher than stated without “prior use” justification by the end user or diverse technology redundancy in the design.

Random Integrity

The Fisher 1061 piston rotary actuator is classified as Type A devices according to IEC 61508, having a hardware fault tolerance of 0. The complete final element subsystem, with a 1061 actuator and rotary valve as the final control element, will need to be evaluated to determine the Safe Failure Fraction of the subsystem. If the SFF for the entire final element subsystem is between 60% and 90%, a design can meet SIL 2 @ HFT=0.

Safety Parameters

For detailed failure rate information refer to the Failure Modes, Effects and Diagnostic Analysis Report for the Fisher 1061 actuator.

Connection of the Fisher 1061 Actuator to the SIS Logic-solver

The final element subsystem (consisting of a positioner, 1061 actuator, and a rotary valve) is connected to the safety rated logic solver which is actively performing the Safety Function as well as any automatic diagnostics designed to diagnose potentially dangerous failures within the 1061 actuator, valve and any other final element components (i.e. Partial Valve Stroke Test).

General Requirements

The system's response time shall be less than process safety time. The final control element subsystem needs to be sized properly to assure that the response time is less than the required process safety time. The 1061 actuator will move the valve to its safe state in less than the required SIF's safety time under the specified conditions.

All SIS components including the 1061 actuator must be operational before process start-up.

The user shall verify that the 1061 actuator is suitable for use in safety applications.

Personnel performing maintenance and testing on the 1061 actuator and valve shall be competent to do so.

Results from the proof tests shall be recorded and reviewed periodically.

The useful life of the 1061 actuator is discussed in the Failure Modes, Effects and Diagnostic Analysis Report for the 1061 actuator.

Installation and Commissioning

Installation

⚠ WARNING

To ensure safe and proper functioning of equipment, users of this document must carefully read all instructions, warnings, and cautions in each applicable instruction manual.

The Fisher 1061 diaphragm rotary actuator must be installed per standard practices outlined in the instruction manual.

The environment must be checked to verify that environmental conditions do not exceed the ratings.

The 1061 actuator must be accessible for physical inspection.

Physical Location and Placement

The 1061 actuator shall be accessible with sufficient room for the valve, actuator, pneumatic connections, any other components of the final control element. Provisions shall be made to allow for manual proof testing.

Pneumatic piping to the actuator shall be kept as short and straight as possible to minimize the airflow restrictions and potential clogging. Long or kinked pneumatic tubes may also increase the valve closure time.

The 1061 actuator shall be mounted in a low vibration environment. If excessive vibration can be expected special precautions shall be taken to ensure the integrity of pneumatic connectors or the vibration should be reduced using appropriate damping mounts.

Pneumatic Connections

Recommended piping for the inlet and outlet pneumatic connections to the 1061 actuator is stainless steel or PVC tubing. The length of tubing between the 1061 actuator and the control device, such as a solenoid valve, shall be kept as short as possible and free of kinks.

Only dry instrument air filtered to 50 micron level or better shall be used.

The process air pressure shall meet the requirements set forth in the installation manual.

The process air capacity shall be sufficient to move the valve within the required time.

Operation and Maintenance

Suggested Proof Test

The objective of proof testing is to detect failures within a 1061 actuator that are not detected by any automatic diagnostics of the system. Of main concern are undetected failures that prevent the Safety Instrumented Function from performing its intended function.

The frequency of proof testing, or the proof test interval, is to be determined in reliability calculations for the Safety Instrumented Functions for which a 1061 actuator is applied. The proof tests must be performed more frequently than or as frequently as specified in the calculation in order to maintain the required Safety Integrity of the Safety Instrumented Function.

The proof test shown in table 1 is recommended. The results of the proof test should be recorded and any failures that are detected and that compromise functional safety should be reported to Emerson Automation Solutions. The suggested proof test consists of a full stroke of the 1061 actuator.

The person(s) performing the proof test of a 1061 actuator should be trained in SIS operations, including bypass procedures, valve maintenance and company Management of Change procedures. No special tools are required.

Table 1. Recommended Full Stroke Proof Test

Step	Action
1	Bypass the safety function and take appropriate action to avoid a false trip.
2	Interrupt or change the signal/supply to the 1061 actuator to force the actuator and valve to perform a full stroke to the Fail-Safe state and confirm that the Safe State was achieved and within the correct time.
3	Restore the supply/signal to the 1061 actuator and confirm that the normal operating state was achieved.
4	Inspect the 1061 actuator and the other final control element components for any leaks, visible damage or contamination.
5	Record the test results and any failures in your company's SIF inspection database.
6	Remove the bypass and restore normal operation.

Repair and replacement

Repair procedures in the 1061 actuator instruction manual must be followed.

Manufacturer Notification

Any failures that are detected and that compromise functional safety should be reported to Emerson. Please contact your Emerson sales office.

Appendix A

Sample Startup Checklist

This appendix provides a sample Start-up Checklist for a 1061 actuator. A Start-up Checklist will provide guidance during the final control elements employment.

Start-Up Checklist

The following checklist may be used as a guide to employ the 1061 actuator in a safety critical SIF compliant to IEC61508.

#	Activity	Result	Verified	
			By	Date
	Design			
	Target Safety Integrity Level and PFD_{AVG} determined			
	Correct valve mode chosen (Fail-closed, Fail-open)			
	Design decision documented			
	Pneumatic compatibility and suitability verified			
	SIS logic solver requirements for valve tests defined and documented			
	Routing of pneumatic connections determined			
	SIS logic solver requirements for partial stroke tests defined and documented			
	Design formally reviewed and suitability formally assessed			
	Implementation			
	Physical location appropriate			
	Pneumatic connections appropriate and according to applicable codes			
	SIS logic solver valve actuation test implemented			
	Maintenance instructions for proof test released			
	Verification and test plan released			
	Implementation formally reviewed and suitability formally assessed			
	Verification and Testing			
	Electrical connections verified and tested			
	Pneumatic connection verified and tested			
	SIS logic solver valve actuation test verified			
	Safety loop function verified			
	Safety loop timing measured			
	Bypass function tested			
	Verification and test results formally reviewed and suitability formally assessed			
	Maintenance			
	Tubing blockage / partial blockage tested			
	Safety loop function tested			

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